MP-PIC Modeling of the Slot Problem

Governing Equations:

Fluid:

Continuity:

$$\frac{\partial}{\partial t}(\rho_f \theta_f) + \nabla \cdot (\rho_f \theta_f \mathbf{u}_f) = 0 \tag{1}$$

Momentum:

$$\frac{\partial}{\partial t}(\rho_f \theta_f \mathbf{u}_f) + \nabla \cdot (\rho_f \theta_f \mathbf{u}_f \mathbf{u}_f) = -\nabla p + \nabla \cdot [\theta_f \mu_f \nabla \mathbf{u}_f]$$
(2)

$$+\nabla \cdot \left[\theta_f \mu_f (\nabla \mathbf{u}_f)^T\right] - \nabla \left\{\frac{2}{3}\theta_f \mu_f \nabla \cdot \mathbf{u}_f\right\} - \mathbf{F} + \rho_f \theta_f \mathbf{g}$$
(3)

where:

- $\rho_f \longrightarrow$ density of the fluid phase
- $\theta_f \longrightarrow$ volume fraction of the fluid phase
- $\mathbf{u}_f \longrightarrow$ velocity of the fluid phase
- $p \longrightarrow \text{pressure}$
- $\mu_f \longrightarrow$ viscosity of the fluid phase
- $\mathbf{g} \longrightarrow$ acceleration due to gravity
- $\mathbf{F} \longrightarrow$ rate of momentum exchange per unit volume between the fluid and particle phases

Equation of Motion of the Particles

$$\frac{d\mathbf{u}_p}{dt} = D_p(\mathbf{u}_f - \mathbf{u}_p) - \frac{1}{\rho_p}\nabla p + \mathbf{g} - \frac{1}{\theta_p \rho_p}\nabla \tau$$
(4)

where:

- $\mathbf{u}_p \longrightarrow$ velocity of the particle
- $\mathbf{u}_f \rightarrow$ velocity of the fluid at particle location
- $\rho_p \longrightarrow$ density of the particle
- $\theta_p \longrightarrow$ volume fraction of the particle phase
- $\tau \longrightarrow$ interparticle stress
- $D_p \longrightarrow \text{drag coefficient}$

 D_p is given by:

$$D_p = C_d \frac{3}{8} \frac{\rho_f}{\rho_p} \frac{|\mathbf{u}_f - \mathbf{u}_p|}{r}$$
(5)

where
$$C_d = \frac{24}{Re} \left(\theta_f^{-2.65} + \frac{1}{6} R e^{2/3} \theta_f^{-1.78} \right)$$
 (6)

Re is the Reynolds number defined as

$$Re = \frac{2\rho_f |\mathbf{u}_f - \mathbf{u}_p|r}{\mu_f} \tag{7}$$

where:

 $r \longrightarrow$ radius of the particle

Interparticle stress τ is given by

$$\tau = \frac{P_s \theta_p^\beta}{\theta_{cp} - \theta_p} \tag{8}$$

where

 $P_s \longrightarrow$ is a constant with units of pressure

 $\beta \longrightarrow \text{constant}$

 $\theta_{cp} \longrightarrow$ is the particle volume fraction at close packing.

In this approach particles are grouped into computational parcels each containing N_p particles with identical density, radius and velocity at a given location, \boldsymbol{x}_p . Particle properties are then mapped to the Eulerian grid for the numerical solution using a bilinear interpolation function.

The particle volume fraction, θ_p , on the Eulerian grid for a given distribution of particles in the domain is given by

$$\theta_{pij} = \frac{1}{V_{ij}} \sum_{p} N_p V_p S(\boldsymbol{x}_p)_{ij}$$
(9)

where:

 $\begin{array}{l} \theta_{pij} \longrightarrow & \text{particle volume fraction at Eulerian grid point } ij \\ V_{ij} \longrightarrow & \text{volume of the Eulerian cell} \\ V_p \longrightarrow & \text{particle volume} \\ S(\boldsymbol{x}_p)_{ij} \longrightarrow & \text{interpolation function} \end{array}$

Similarly the fluid-particle momentum exchange is given by

$$\mathbf{F}_{ij} = \frac{1}{V_{ij}} \sum_{p} S_{ij}[\boldsymbol{x}_p] \left\{ D_p(\mathbf{u}_f - \mathbf{u}_p) - \frac{1}{\rho_p} \nabla p \right\} N_p m_p \tag{10}$$

where:

 $m_p \longrightarrow$ mass of the particle

Equation for particle position:

Particle position is updated using the following equation:

$$\frac{d\boldsymbol{x}_p}{dt} = \mathbf{u}_p \tag{11}$$

For more details please see: Andrews, M.T. & O'Rourke, P.J., 1996, "The multiphase particle-in-cell (MP-PIC) method for dense particle flow," Int. J. Multiphase Flow, vol 22, pp. 379–402.

We solved the system of equations using control-volume method with staggered grids for velocity and pressure.

Results

2D:

In Figure 1 we have presented the result for a 2D simulation of the slot problem.

We have a channel of length, x = 5mchannel height, y = 0.25mGravity acts in negative y direction Fluid particle mixture enters the channel at x = 0Inlet velocity of the mixture = 0.062m/sFluid density, $\rho_f = 1000 \text{ kg/m}^3$ Particle density, $\rho_p = 1400 \text{ kg/m}^3$ Particle radius, r = 0.03 cmFluid viscosity, $\mu_f = 0.025 \text{ N-s/m}^2$

29 new parcels enter the computational domain at x = 0 at each time-step. dt = 0.14s. Parcels are equally spaced along the channel height. Each parcel has 4063 particles.

Thus $N_p = 4063$. Concentration of the particles flowing in = 0.0491 **3D:**

In Figures 2a - 2c we have presented the results for a 3D simulation of the slot problem.

The channel is shown below.

Gravity acts in negative y direction Fluid particle mixture enters at z = 0Inlet velocity = 0.062 m/s $\rho_f = 1000 \text{ kg/m}^3$ $\rho_p = 1400 \text{ kg/m}^3$ r = 0.03 cm $\mu_f = 0.025 \text{ N-s/m}^2$

145 new parcels enter the computational domain at z = 0 at each time step. dt = 0.14s.

The parcels are positioned at equally spaced 29 locations along the height of the channel and equally spaced 5 locations along the width of the channel.

Each parcel has 3 particles.

Concentration of the particles flowing in = 0.029. At the instant presented in Figures 2a-2c, time, t = 12.6s.

Total number of parcels = 13050

Figure 2a shows the parcels inserted in the channel at z = 0. Parcels are inserted at 29 locations along the height of the channel. As they move forward in the z direction with the flow they fall due to gravity acting in the negative y direction.

Figure 2b shows the parcels in the y-x planes which is perpendicular to the direction of flow. Parcels are inserted at 5 locations along the width of the channel. This is indicated by 5 vertical lines of higher parcel concentration. As the parcels fall in the negative y direction they disperse from their original x-location in the channel.

Figure 2c shows the parcels in the z-x planes.





Figure 2b: View in the y-x planes for the 3 dimensional simulation. Gravity acts in negative y direction. (Dimensions are not to scale)

Υ

- x

x axis parallel to channel width (=0.0063m)

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Figure 2c: View in the z-x planes for the 3 dimensional simulation. Flow comes in at z=0 plane. (Dimensions are not to scale)



x axis parallel to channel width (=0.0063m)





Figure 2a: View in the y-z planes for the 3 dimensional simulation. Flow comes in at z=0 plane. Gravity acts in negative y direction. (Dimensions are not to scale)

Υ

Ζ

z-axis parallel to channel length (=5m)

10