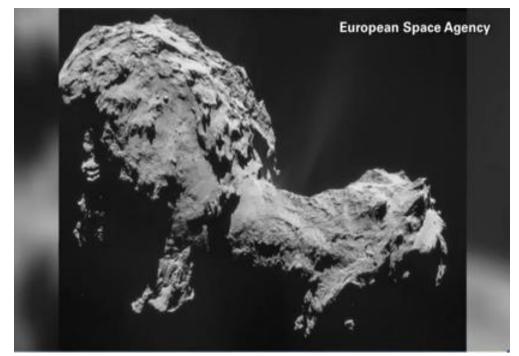
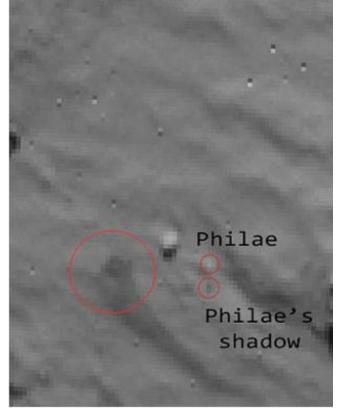
AEM 1905: Some considerations for EDL (entry, descent, landing)

- high/low gravity; thick/thin/no atmosphere; altitude of landing zone
- parachutes or descent (retro-rocket) engines or gliding vehicle (space shuttle)
- lift (e.g. the Curiosity lander threw off tungsten mass to gain some angle of attack)
- landing (target) ellipse
- autonomous (if unmanned landing on a distant target)
- solid surface, liquid surface, gas-only
- heat shield (often ablative)
- **Mars**: thin atmosphere, high mach number drogue, retro-rocket/powered descent, dust/wind issues, air bags vs sky crane, MER http://www.youtube.com/watch?v=-9BYSDtwRc, MSL https://www.youtube.com/watch?v=-KLxmGLZQSY (narrated by AEM alum Steve Lee, JPL)
- Moon: no atmosphere, powered descent, dust, touch sensors, ascent stage
- **Earth**: thick atmosphere, skip re-entry, splash-down vs bump-down (with retrorockets), multi-stage parachutes (for humans) http://www.youtube.com/watch?v=VvObe2XxJ1s
- **Jupiter**: thick atmosphere (won't reach the bottom of the atmosphere "alive")
- Venus: thick atmosphere, exceptionally hot surface
- Comet 67P: no atmosphere, exceptionally low gravity, 2-hour bounce!

Rosetta mission – the Philae lander









Rosetta mission – the Philae lander

17 November 2014 Last updated at 09:39 ET



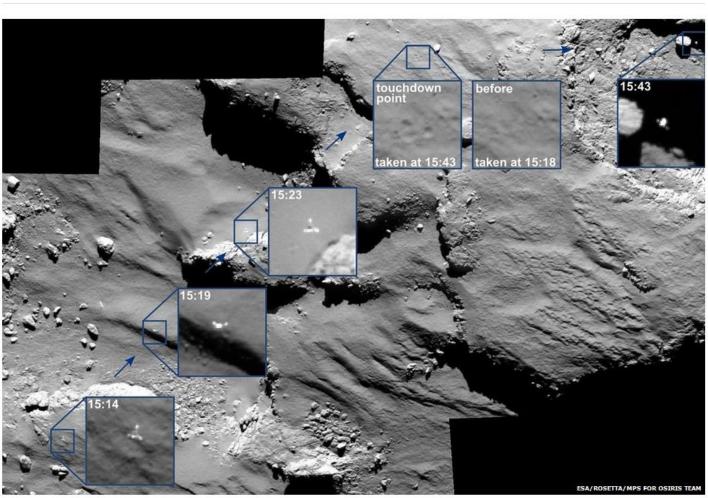




Comet lander: Camera sees Philae's hairy landing

By Jonathan Amos

Science correspondent, BBC News

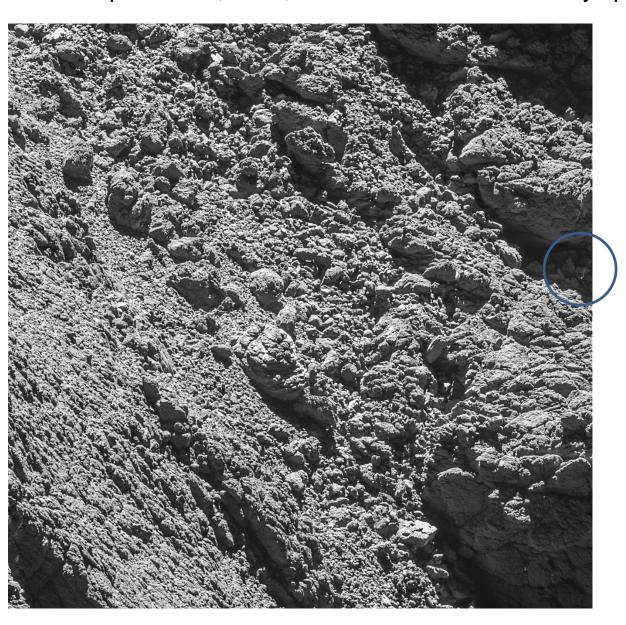


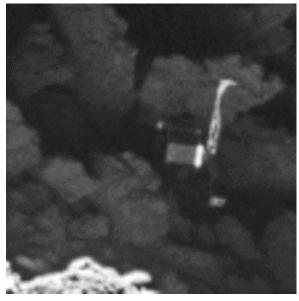
This collection of images was acquired when Rosetta was about 15km above the surface of 67P

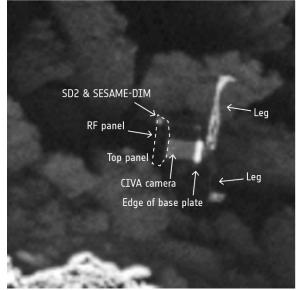
High-resolution pictures have now been released of the Philae probe in the act of landing on Comet 67P last Wednesday.

Rosetta mission – an update

On September 2, 2016, the Philea lander was finally spotted on the surface!

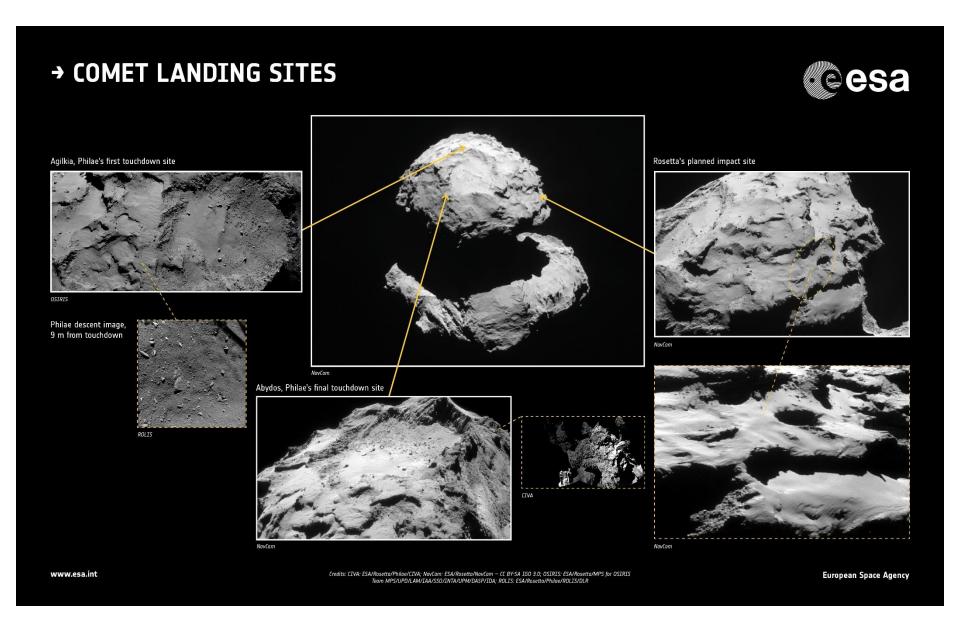






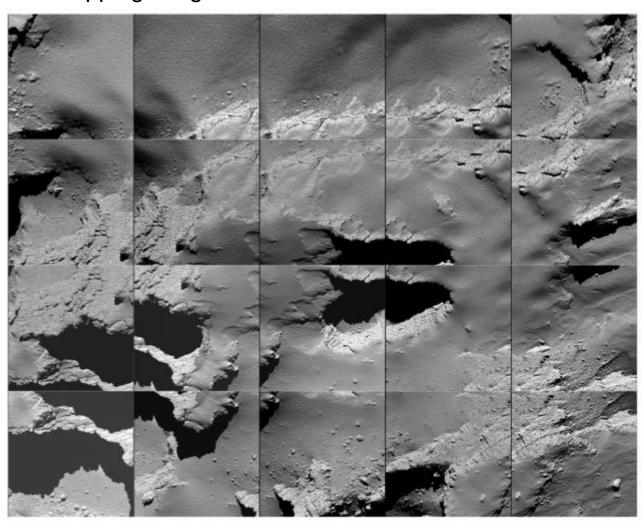
Rosetta mission – an update

On September 30, 2016, the Rosetta spacecraft was intentionally crashed.



Rosetta mission – an update

Overlapping images taken on descent. About 1 km across.



Final image from 20 m. About 1 m across.

